

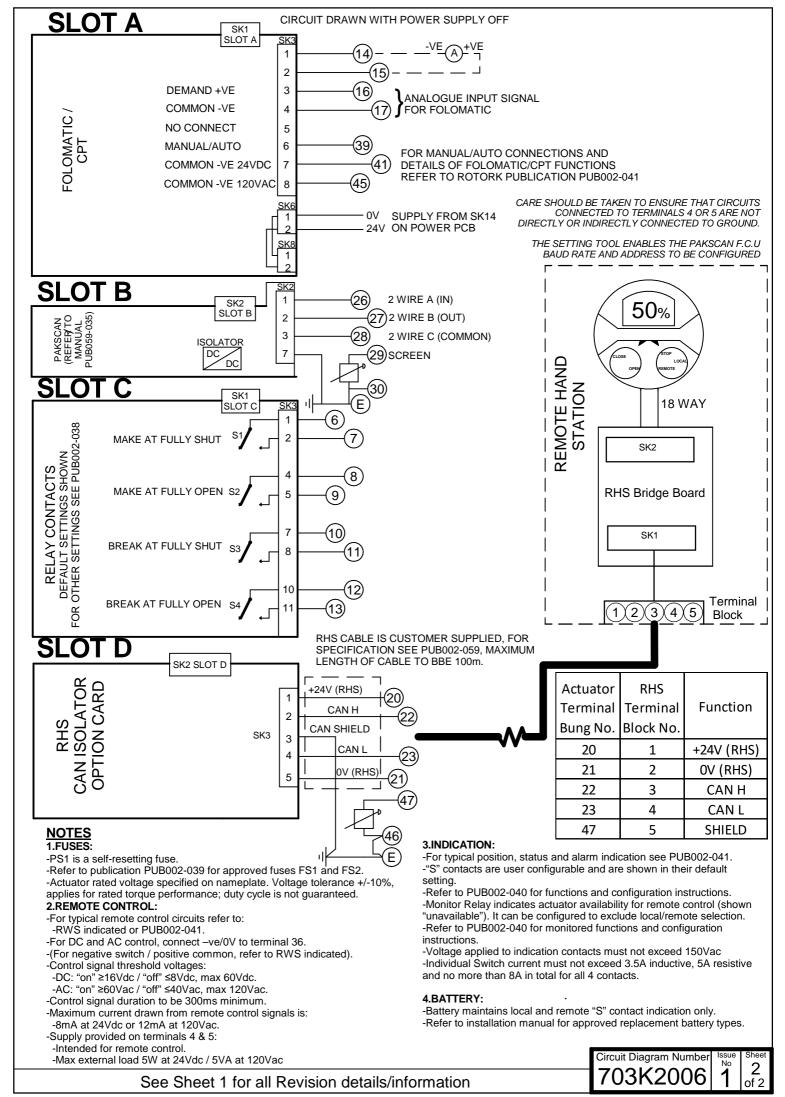
Independently Certified to IEC61508-2 (2010) as an element suitable for use in safety related systems up to and including SIL 2 (1001) and SIL 3 (1002). Must

high demand safety function, actuator will not move spuriously.

SIL MOVE TO LIMIT (Safety Function 2): The control signal must be removed to terminal 25 to cause the actuator to move to the configured end of travel position (Open or Close limit). This is not a maintained input, SF2 control signal must be removed for the duration of operation to the configured limit position. This is a low demand safety function.

If the safety function is configured for SIL MOVE TO LIMIT (SF2) ONLY, terminal 34 will be a standard Stop/Maintain input in accordance with PUB002-041. Safety Function 1 + Safety Function 2: Where both safety functions are required, the priority and functions must be configured in accordance with the SIL Safety Manual - PUB002-057. The common for SF1 (terminal 36) and SF2 (terminal 31) are independent allowing the control signal to be derived from separate, independent systems. If required, where signals are derived from the same system, the commons can be linked together. SF1 and SF2 Signals must be within the range 16-60VDC, positive supply switched only

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<u>ls</u>	<u>Date</u> 250124		Revision Details FIRST ISSUE	www. rot	OFK.com	IQ + SIL + FOLOMATIC & CPT + PAKSCAN + RHS				
				BATH, BA1 3JQ	ROTORK CONTROLS INC ROCHESTER NY 14624, USA Tel:585-247-2304	Date : 250124 Base WD: 703K2006 Job No :	Circuit Diagram Number 703K2006 B1 C1 B2 C2 B1 C1 M1 V1	Issue No	Sheet 1 of 2	



IQ3